Aerosol retrievals in partially clouded scenes

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Why partially clouded scenes?

Most current aerosol retrieval algorithms are developed for retrievals above homogeneous cloud fields or clear sky scenes.

The latter requires a priori cloud screening;

- filter too strict and lose data, especially
 - near-cloud scenes (increased AOT)
- filter too loose and end up with a 'contaminated' data-set
 - erratic retrievals (overestimated AOT for example)



Illustration of the 'twilight' zone [Koren et. al., 2007, GRL].

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Goal & outline

Goal

► Further develop the aerosol retrieval algorithm (intended for clear sky scenes) to account for partial cloud cover, so it can retrieve aerosol properties in cloud contaminated scenes.

Today

 Intermediate step: Retrievals on partially clouded scenes (with original algorithm) to asses the sensitivity to and the effect of cloud contamination.

Method

measurement

Multi-angle observations of intensity and polarization.

POLDER-3 (POLarization and Directionality of Earth's Reflectances) on board PARASOL (Polarization and Anisotropy of Reflectances for Atmospheric Science coupled with Observations from Lidar).





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Method

aerosol & ocean parameters

Fine & Coarse Aerosol mode;

variable	explanation
R _{eff}	Effective radius
V_{eff}	Effective variance
Mr	Reflection index (real)
Mi	Reflection index (im.)
N _c	Column density
S	frac. spher. particles
	(coarse mode only)

Ocean parameters;

variable	explanation
V_x	wind speed in x
V_y	wind speed in y
Foam _{frac}	foam fraction
Foam _{alb}	foam albedo
Chla	Chlorophyll-a



Micrographs, courtesy USGS, UMBC (Chere Petty), and Arizona State University (Peter Buseck).

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Method

Philips-Tikhonov regularization

- Initial guess aerosol & surface/ocean parameters (LUT)
- Calculate optical properties of aerosol & surface/ocean
- Do radiative transfer calculation & obtain Jacobian
- Compare with actual measurement
- Minimize cost function

$$\hat{x} = \min_{x} \left(||S_{y}^{-\frac{1}{2}} (F(x) - y)||^{2} + \gamma ||W(x - x_{\alpha})||^{2} \right)$$

- Iterate these step until convergence
- filter the result based on χ^2 (i.e. goodness of fit)



Co-locate MODIS & PARASOL data and use cloud properties from MODIS for the analysis.

<code>PARASOL</code> : 6.2x6.2 km pixel (full res.) or 19x19km km pixel (medium res.) MODIS : ${\sim}1x1$ km pixel

4 levels in MODIS cloud mask: -conf. cloudy, -prob. cloudy, -prob. clear, -conf. clear

we use : f = conf. cloudy + prob. cloudy

An example



A clear sky measurement at 865 nm (χ^2 = 5.8)

Inhomogeneities at different scattering angles





An measurement at 865 nm of a scene that was inhomogeneous at the different scattering angles (χ^2 =196.7).



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An measurement at 865 nm of a scene that was inhomogeneous at the different scattering angles ($\chi^2{=}351.7).$

Inhomogeneities at different scattering angles



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An example



Results

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Validation against 10 AERONET stations overlooking the ocean;

Anmyon, Forth Crete, Gosan SNU, Guam, Midway Island, Muscat, Shirahama, Trelew, Trinidad Head & Sevastopol.

Max distance 40 km Max time diff. 1 hr

Validate the;

- AOT
- SSA
- Ångström exponent
- Real refractive Index.



Figure: An AERONET sunphotometer overlooking the ocean.

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AOT comparison



Figure: The median of the coincidently retrieved AOT at 670 nm, with the range in gray. Extra filter; meas. with $AOT_{670} > 5.0$ discarded.

Ångström exponent comparison



Figure: The median of the coincidently retrieved Ångström exponents at 490 nm / 670 nm, with the range in gray. Extra filter to discards measurements with $AOT_{670} < 0.1$.

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SSA comparison



Figure: The retrieved single scattering albedo at 670 nm near Forth Crete, with the range in gray. Extra filter to discards measurements where the Avg. Ker. of $m_{i,f} < 0.1$.

Conclusion

The original algorithm is sensitive to clouds. room to fit water clouds

 Clouds can be effectively screened out on basis of a goodness of fit criterion.

the rainbow feature plays a role here

- Less near-cloud scenes and scenes with a high aerosol load are discarded.
- Retrieved AOT, SSA, Ångström exponent & Refractive indices compare well to AERONET observations.

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Outlook

- Improve 3-mode retrieval (fitting COT)
- Check validity of cloud in model (neglected 3D effects, etc)

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extra slides

Comparison of the real refractive index

By AERONET a real refractive index is retrieved for 1 mode.

By our algorithm, two real refractive indices are retrieved (1 per mode).

We can only compare our total particle volume weighted real refractive index with AERONET;

$$m_{comb} = \frac{V_{fine} m_{r,fine} + V_{coarse} m_{r,coarse}}{V_{fine} + V_{coarse}}$$
(1)

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Figure: The median of the coincidently retrieved real refractive index¹ near Forth Crete

3-mode retrievals

including a cloud in the algorithm

Include cloud by adding a 3rd mode, representing water droplets. gamma-size distribution (instead of log-normal)

parameter	value
R _{eff}	use MODIS data or apriori
V_{eff}	fixed at 0.1 μ m
M _r	fixed (wavelength dependent [Segelstein, 1981])
Mi	fixed (wavelength dependent [Segelstein, 1981])
N _c	-
S	fixed at 1.0
f	use MODIS data

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3-mode retrievals

preliminary results



A Med. Res. PARASOL observation & fit at 865 nm (χ^2 =6.8).

3-mode retrievals

preliminary results



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A Medium Resolution PARASOL measurement at 865 nm (χ^2 =10.7).